Electromagnetic Wave and Radiating System CT - 1

 Last edited time 	@January 30, 2024 6:44 PM	
 Created 	@December 3, 2023 6:23 PM	
i≣ Tags	CSTE	Year 2 Term 2
Created by	B Borhan	

Electromagnetic Wave: Electromagnetic Waves or EM waves are waves that are created as a **result of vibrations an electric field and a magnetic field**.

Microwave: Microwave are defined as electromagnetic radiations with a **frequency ranging between 300MHz to 300 GHz.** Example : Satellite communication signal.

Del Operator / Nabla Operator

Also known as vector differential operator.

- · collection of partial derivative operators
- a metatheatrical operator commonly used in vector calculus
- "Operator" is similar to a function
- It's defined as a vector, but it doesn't have magnitude. So, it isn't a "true" vector.

$$abla = rac{\delta}{\delta x}i + rac{\delta}{\delta y}j + rac{\delta}{\delta z}k$$

Uses of Del operator

• **Gradient :** The gradient of a scalar field is a vector that points in the direction in which the field is most rapidly increasing, with the scalar part equal to the rate of change.

 $Gradient = \vec{\nabla} \vec{V}$

• **Divergence:** A divergence shows how the field behaves towards away from a point. The divergence of a vector field is scalar field.

 $Divergence = \vec{\nabla}.\vec{V}$

• **Curl:** A curl is used to measure the rotational extent of the field about a particular point. The curl of a vector field is a vector field.

Curl = ec
abla imes ec V

$$abla imes \mathbf{F} = egin{bmatrix} oldsymbol{\hat{i}} & oldsymbol{\hat{j}} & oldsymbol{\hat{k}} \ rac{\partial}{\partial x} & oldsymbol{\partial}{\partial y} & oldsymbol{\partial}{\partial z} \ F_x & F_y & F_z \end{bmatrix}$$

The Divergence Theorem :

The divergence theorem states that the surface integral of the normal component of a vector point function F over a closed surface S is equal to the volume integral of the divergence of \vec{F}

$$\int_x \int_y \int_z ec
abla . ec F \ dec v = \int_v ec
abla . ec F \ dec v = \oint_s ec F \ . \ dec s$$

Example: Compute $\iint_{S} F dS$, where $F = (3x + z, y^2 - \sin x^2 z, xz + ye^{x^5})$, where $0 \le x \le 1, 0 \le y \le 3, 0 \le z \le 2$

Solution:

 $\operatorname{div} \mathbf{F} = 3 + 2\mathbf{y} + \mathbf{x}.$

∬s F dS =∭B div F dV

Given interval is: $0 \le x \le 1$, $0 \le y \le 3$, $0 \le z \le 2$

Now substitute the intervals in the lower and the upper limits of the integrals, then we have:

 $\iint s F dS = \int_0^1 \int_0^3 \int_0^2 (3 + 2y + x) dz dy dx$

Integrate the function with respect to z and substitute the limits.

 $=\int_0^1\int_0^3(6+4y+2x) dy dx$

Now, integrate with respect to x and y, and substitute the limits, we get:

$$= 36 + 3$$

= 39

Thus, $\iint_{S} F dS = 39$.

Stokes Theorem

Statement: The surface integral of the curl of a function over a surface bounded by a closed surface is equal to the line integral of the particular vector function around the

surface.

Using stokes theorem, evaluate:

 $\int \int_{S} curl \vec{F} \cdot d\vec{S}$, where $\vec{F} = xz\hat{i} + yz\hat{j} + xy\hat{k}$, such that S is the part of the sphere $x^2 + y^2 + z^2 = 4$ that lies inside the cylinder $x^2 + y^2 = 1$ and above the xy-plane.

Solution:

Given,

Equation of sphere: $x^2 + y^2 + z^2 = 4$(i)

Equation of cylinder: $x^2 + y^2 = 1....(ii)$

Subtracting (ii) from (i),

 $z^2 = 3$

 $z = \sqrt{3}$ (since z is positive)

Now,

The circle C is will be: $x^2 + y^2 = 1$, $z = \sqrt{3}$

The vector form of C is given by:

 $egin{aligned} r(t) &= cost\hat{i} + sint\hat{j} + \sqrt{3}\hat{k}; 0 \leq t \leq 2\pi \end{aligned}$ $Thus, \ r'(t) &= -sint\hat{i} + cost\hat{j} \end{aligned}$ Let us write $\mathsf{F}(\mathsf{r}(\mathsf{t}))$ as: $F(r(t)) &= \sqrt{3}cost\,\hat{i} + \sqrt{3}sint\,\hat{j} + cost\,sint\,\hat{k} \end{aligned}$

$$\iint_{S} \operatorname{curl} \mathbf{F} \cdot d\mathbf{S} = \int_{C} \mathbf{F} \cdot d\mathbf{r}$$
$$= \int_{0}^{2\pi} \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt$$
$$= \int_{0}^{2\pi} \left(-\sqrt{3} \cos t \sin t + \sqrt{3} \sin t \cos t \right) dt$$
$$= \sqrt{3} \int_{0}^{2\pi} 0 dt$$
$$= 0$$

Electric Field

- a vector field
- the force per unit charge exerted/applied on a positive test charge at rest at a specific point

$$E = \frac{F}{q}$$

Electric Displacement Vector

- is the charge per unit area that would be displaced across a layer of conductor placed across an electric field
- denoted by *D*

 $D = \epsilon_0 E + P$

Polarization density, $P = \frac{\Delta p}{\Delta V}$

 $\Delta p = ext{dipole moment} \ \Delta V = ext{volume element}$

Isotropic medium

- all properties are uniform and independent of direction
- does not depend on the direction
- the velocity of light is the same in all direction
- Example : Glass

Anisotropic medium

- the properties are different in all direction
- direction-dependent
- the velocity of light differs according to direction

Ampere's Circuit Law: The line integral of Magnetic field intensity along a closed path is equal to the current distribution passing through that loop.

 $\oint H \cdot dL = I_{enc} = \iint J \cdot ds$ $J = ext{current density}$

Maxwell Four Equation

Maxwell first equation: $\vec{\nabla}.\vec{D} = \rho_v$

Statement : The total electric displacement through the surface enclosing a volume is equal to the total charge with the volume. The more charge density the more

Electric field.

 $\oint \vec{D} \cdot d\vec{s} = Q_{enc} \dots (1)$ $\oint \oint \vec{D} \cdot d\vec{s} = \iiint \nabla \cdot \vec{D} d\vec{v} \dots (2) [\text{from Divergence theorem}]$ $\iiint \nabla \cdot \vec{D} d\vec{v} = Q_{enc} \dots (3) [\text{from equation 1 and 2}]$

The volume charge density,

 $egin{aligned} &
ho_v = rac{dQ}{dv} \ ext{or}, \, dQ =
ho_v dv \ ext{or}, \, Q = \int\!\!\!\!\int\!\!\!\int
ho_v dv \end{aligned}$

$$\iint ec
abla . ec D dec v = \iint
ho_v d \
abla . D =
ho_v$$

Maxwell Second equation $ec{ abla} \cdot ec{B} = 0$

Statement: The total outward flux of magnetic induction (B) through any closed surface is equal to zero.

From Gauss's Law,
$$\oint ec{B} \cdot dec{A} = 0$$

 $\oint ec{B} \cdot dec{A} = \int_v ec{
abla} . ec{B} dec{v} = ec{
abla} . ec{B} = 0$

<u>Maxwell Third equation:</u> $ec{ abla} imes ec{E} = -rac{dec{B}}{dt}$

Statement: The electromotive force around a closed path is equal to negative rate of change of magnetic flux linked with the path. That means change of magnetic flux will create the electric field.

Faraday's Law,
$$\epsilon_{emf} = -\frac{d\phi}{dt}$$

Gauss Law, $\epsilon_{emf} = \oint_c \vec{E}.dl$
 $\oint_c \vec{E}.dl = -\frac{d\phi}{dt} = \frac{d\oint_S - \vec{B}.da}{dt} = -\oint_S \frac{d\vec{B}}{dt}da$
or, $\oint_S \vec{\nabla} \times \vec{E} \, da = -\oint_S \frac{d\vec{B}}{dt}da$
or, $\oint_S (\vec{\nabla} \times \vec{E} + -\frac{d\vec{B}}{dt}) \, da = 0$
or, $\vec{\nabla} \times \vec{E} = -\frac{d\vec{B}}{dt}$

<u>Maxwell Fourth Equation or Maxwell-Ampere's Law:</u> $ec{ abla} imes ec{H} = ec{J} + rac{\deltaec{D}}{\delta t}$

Statement: The magnetomotive force around a closed path is equal to the summation of conductor current and displacement current through any surface bounded by the path. Changing electric field creates magnetic field.

Ampere's circuit law, $\oint_c \vec{B}.\vec{dl} = \mu_0 i$ By Stroke's theorem, $\oint_c \vec{B}.\vec{dl} = \oint_S (\vec{\nabla} \times \vec{B})\vec{dS}$ $\oint_S (\vec{\nabla} \times \vec{B})\vec{dS} = \mu_0 i = \mu_0 \oint_S \vec{J}.\vec{dS}$ or, $\oint (\vec{\nabla} \times \vec{B} - \mu_0 \vec{J})\vec{dS} = 0$ or, $\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$ or, $\vec{\nabla} \times \vec{H} = \vec{J}$

Modified Ampere's circuit law,

 $\oint_c ec{B}.ec{dl} = \mu_0 i + i_d \ [i_d: ext{displacement current}]$ $ec{
abla} imes ec{H} = ec{J} + ec{J}_d = ec{J} + \epsilon_0 rac{\delta ec{E}}{\delta t} = ec{J} + rac{\delta ec{D}}{\delta t} \ [E = rac{D}{\epsilon_0}]$

Derive equation of continuity by Maxwell's 4th equation

$$egin{aligned} ec{
abla} imes ec{H} &= ec{J} + rac{\delta D}{\delta t} \ ext{or, } 0 &= ec{
abla}.(ec{J} + rac{\delta D}{\delta t}) \ ext{or, } ec{
abla}.ec{J} &= -rac{\delta
ho}{\delta t} \end{aligned}$$

Why Ampere's Law is not correct ?

Ampere's Law is valid only for steady current or when the electric field does not change with time.

$$\vec{\nabla}.\vec{J} = -\frac{\delta\rho}{\delta t}$$
, equation of continuity
From Maxwell fourth equation, $\vec{\nabla} \times \vec{H} = \vec{J}$
or, $\vec{\nabla}.(\vec{\nabla} \times H) = \vec{\nabla}.\vec{J}$
or, $\vec{\nabla}.\vec{J} = 0$, $[\vec{\nabla}(\vec{\nabla} \times H) = 0]$ it doesn't match with continuity equation.

Drawback of Ampere's Law

- applicable for constant current or when the electric field does not vary the time
- valid only for the points where there is only conduction current and no displacement current
- doesn't match with continuity equation

Problems:

• **Type 1:** Electron and proton number is given and you have to calculate the electric flux.

Find the electric flux through the surface of a sphere containing m protons and n electrons.

$$egin{aligned} {
m Flux}, \phi_E &= rac{q_{enc}}{\epsilon_0}, \ q_{enc} &= m \cdot q_p + n \cdot q_e \ q_p &= 1.6 imes 10^{-19}, q_e = -1.6 imes 10^{-19}, \epsilon_0 = 8.85 imes 10^{-12} \end{aligned}$$

• **Type 2:** Surface Charge density and x, y is given

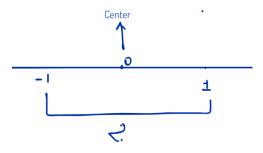
A cube of side L contains a flat plate with variable surface charge density, $\rho = -3xy$. If the plate extends from x = 0 to L and y = 0 to M. What is the total electric flux through the wall of the cube ?

$$\phi_E=rac{q_{enc}}{\epsilon_0}$$
 $q_{enc}=\int_s
ho da=\int_{y=0}^M\int_{x=0}^L-3xy\ dxdy$ = ... [Applicable for continuous charge]

- Type 3: Electric Flux density is given and find the charge density ho

The electric flux density is given as, $\vec{D} = x^3 \hat{i} + x^2 y \hat{j}$. Find the charge density ρ inside a cube of side 2m placed centered at the origin with its side along the

co-ordinate axes.



• Type 4: Sphere

$$egin{aligned} dv &= r^2 sin heta dr d heta d\phi \left[0 < r < 2, \; 0 < heta < \pi, 0 < \phi < 2\pi
ight] \ \int uv dx &= u \int v dx - \int (u' \int v dx) dx \end{aligned}$$

The volume charge density inside a hallow sphere is $\rho = 10e^{-30\pi} \text{cm}^{-2}$. Find the total charge enclosed within the sphere. Also find electric flux density on the surface of the sphere.

$$egin{aligned} Q &= \int_v
ho dv = \int_{\phi=0}^{2\pi} \int_{ heta=0}^{\pi} \int_{r=0}^{2} 10 e^{-20\pi} r^2 sin heta dr d heta d\phi = rac{\pi}{100} \ D &= \epsilon.E = rac{1}{4\pi r^2} \cdot rac{\pi}{100} = rac{1}{400r^2} \end{aligned}$$

• Type 5:

In a conducting medium the magnetic field is given as $H = y^2 x \hat{i} + 2(x + 1)yz\hat{j} - (x + 1)z^2\hat{k}$. Find the conduction current density (J) at point (2,0,-1); Also find the current y = 1, 0 < x < 1, 0 < z < 1.

$$J=ec
abla imes ec H=egin{bmatrix} \hat{i} & \hat{j} & \hat{k} \ rac{\delta}{\delta x} & rac{\delta}{\delta y} & rac{\delta}{\delta z} \ y^2 x & 2(x+1)y^3 & -(x+1)z \end{bmatrix}$$

 $=-(2xy+2y)\hat{i}+(z^2+y^2)\hat{j}$ At point $(2,0,-1),J=\hat{j}$ At $y=1,ec{J}=(1-z^2)\hat{j}$

$$I = \int_{S} ec{J} dA = \int_{z} \int_{x} J dx dy = \int_{0}^{1} \int_{0}^{1} \hat{(1+z^2)} dx dz = rac{2}{3}A$$

• Type 6: EMF

Find the emf induced in a square loop with sides of length lying in the yz plane is a region in which magnetic field charge overtime, $B(t) = B_0 e^{-5t/t_0} \hat{i}, \epsilon = \frac{-d}{dt} \int_s \vec{B} \ \hat{\eta} \ \vec{d}a$, unit normal $\hat{\eta} = \hat{i}$.

$$egin{aligned} & \mathrm{emf} = -rac{d}{dt}\int_{s}ec{B}\cdotec{\eta}\ dec{a} = -rac{d}{dt}\int_{s}B_{0}e^{-5t/t_{0}}\hat{i}.\hat{i}dec{a} \ & = -rac{d}{dt}B_{0}e^{-5t/t_{0}}\int_{s}da \ & = -rac{d}{dt}B_{0}e^{-5t/t_{0}}a^{2} \ & = rac{5a^{2}B_{0}}{t_{0}}e^{-5t/t_{0}} \end{aligned}$$